## Carleton College, winter 2014 Math 232, Solutions to practice midterm 2 Prof. Jones

1. Find a bases for the kernel and image of the following matrix:

$$A = \left[ \begin{array}{rrrrr} 1 & 0 & 2 & 0 & 1 \\ -3 & 0 & 0 & 1 & 0 \\ -1 & 0 & 4 & 1 & 2 \end{array} \right].$$

To find a basis for the kernel, we need to row reduce the augmented matrix

$$\left[\begin{array}{ccc|ccc|c}
1 & 0 & 2 & 0 & 1 & 0 \\
-3 & 0 & 0 & 1 & 0 & 0 \\
-1 & 0 & 4 & 1 & 2 & 0
\end{array}\right],$$

and we get the reduced row-echelon form

$$\left[\begin{array}{cccc|cccc}
1 & 0 & 0 & -1/3 & 0 & 0 \\
0 & 0 & 1 & 1/6 & 1/2 & 0 \\
0 & 0 & 0 & 0 & 0 & 0
\end{array}\right],$$

Thus the free variables are  $x_2, x_4$ , and  $x_5$ , and we set  $x_2 = t_1, x_4 = t_2$ , and  $x_5 = t_3$ . The set of solutions is then

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} \frac{1}{3}t_2 \\ t_1 \\ -\frac{1}{6}t_2 \\ t_2 \end{bmatrix}.$$

Separating the arbitrary constants  $t_1, t_2, t_3$  into their own vectors then yields a basis of

$$\left\{ \begin{bmatrix} 0\\1\\0\\0\\0 \end{bmatrix}, \begin{bmatrix} 1/3\\0\\-1/6\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\-1/2\\0\\1 \end{bmatrix} \right\}.$$

As for the image, the above reduced row-echelon form shows that the non-redundant columns are the first and the third, so a basis for the image is

$$\left\{ \begin{bmatrix} 1\\ -3\\ -1 \end{bmatrix}, \begin{bmatrix} 2\\ 0\\ 4 \end{bmatrix} \right\}.$$

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2. Find a basis for the following subspace of  $P_4$ .

$$W = \{ p(x) \in P_4 \mid p(1) = p(-1) = 0 \}.$$

What is the dimension of W?

Note that W is the same as

$${a_4x^4 + a_3x^3 + a_2x^2 + a_1x + a_0 \in P_4 \mid a_4 + a_3 + a_2 + a_1 + a_0 = 0, a_4 - a_3 + a_2 - a_1 + a_0 = 0}.$$

There are different ways to do this problem, but the most systematic is to find all solutions to the system of equations

So we put the augmented matrix

$$\left[\begin{array}{ccc|cccc}
1 & 1 & 1 & 1 & 1 & 0 \\
1 & -1 & 1 & -1 & 1 & 0
\end{array}\right]$$

in reduced row-echelon form. We get

Thus our free variables are  $a_2$ ,  $a_3$ , and  $a_4$ . Set  $a_2 = t_1$ ,  $a_3 = t_2$ , and  $a_4 = t_3$ . The set of solutions is then

$$\begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} -t_1 & -t_3 \\ -t_2 \\ t_1 & \\ & t_2 \\ & & t_3 \end{bmatrix}.$$

Separating the arbitrary constants  $t_1, t_2, t_3$  into their own vectors then yields a basis of

$$\left\{ \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

But we need to re-convert these to polynomials, since W is a subspace of  $P_4$ , and hence any basis for it should consist of elements of  $P_4$ . So a basis for W is

$$\{-1+x^2, -x+x^3, -1+x^4\},\$$

and W has dimension 3.

3. Determine whether the following mappings are linear transformations. Either prove that a given map is linear or give a counterexample to show it's not linear.

(a) 
$$T: \mathbb{R}^2 \to \mathbb{R}^3$$
 defined by  $T((x_1, x_2)) = (2x_1, x_1 + 4, 5x_2)$ 

Not linear since 2T((0,0)) = 2(0,4,0) = (0,8,0) but T(2(0,0)) = T((0,0)) = (0,4,0).

(b) 
$$T: P_2 \to P_3$$
 defined by  $T(a_2x^2 + a_1x + a_0) = a_0x^3 + (a_1 - a_0)x^2 + 3a_2 - (1/2)a_0$ 

Linear. Let  $\vec{u} = u_2 x^2 + u_1 x + u_0$  and  $\vec{v} = v_2 x^2 + v_1 x + v_0$ . Then

$$T(\vec{u} + \vec{v}) = (u_0 + v_0)x^3 + (u_1 + v_1 - u_0 - v_0)x^2 + 3(u_2 + v_2) - (1/2)(u_0 + v_0)$$

$$= (u_0x^3 + (u_1 - u_0)x^2 + 3u_2 - (1/2)u_0) + (v_0x^3 + (v_1 - v_0)x^2 + 3v_2 - (1/2)v_0)$$

$$= T(\vec{u}) + T(\vec{v})$$

A similar calculation shows that  $T(c\vec{u}) = cT(\vec{u})$ .

4. Let V be a subspace of  $\mathbb{R}^n$  with  $\dim(V) = n$ . Explain why  $V = \mathbb{R}^n$ .

Since  $\dim(V) = n$ , V has a basis B containing n elements. Since B is a basis for V, B is linearly independent. However, n linearly independent vectors in the n-dimensional space  $\mathbb{R}^n$  must form a basis for  $\mathbb{R}^n$ , by Theorem 3.3.4(c). Thus B is a basis for both V and  $\mathbb{R}^n$ , and so  $\operatorname{Span}(B) = V$  and  $\operatorname{Span}(B) = \mathbb{R}^n$ . Hence  $V = \mathbb{R}^n$ .

5. (a) Consider the mapping  $T: \mathbb{R}^{2\times 2} \to \mathbb{R}^{2\times 2}$  defined by

$$T\left(\begin{array}{cc}a&b\\c&d\end{array}\right)=\left(\begin{array}{cc}a+b&c-b\\b+2d-3c&d+4a\end{array}\right).$$

Prove that T is a linear transformation.

Let

$$\vec{u} = \begin{pmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{pmatrix} \qquad \vec{v} = \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix}$$

Then

$$T(\vec{u} + \vec{v}) = \begin{pmatrix} u_{11} + v_{11} + u_{12} + v_{12} & u_{21} + v_{21} - (u_{12} + v_{12}) \\ u_{12} + v_{12} + 2(u_{22} + v_{22}) - 3(u_{21} + v_{21}) & u_{22} + v_{22} + 4(u_{11} + v_{11}) \end{pmatrix}$$

$$= \begin{pmatrix} u_{11} + u_{12} & u_{21} - u_{12} \\ u_{12} + 2u_{22} - 3u_{21} & u_{22} + 4u_{11} \end{pmatrix} + \begin{pmatrix} v_{11} + v_{12} & v_{21} - v_{12} \\ v_{12} + 2v_{22} - 3v_{21} & v_{22} + 4v_{11} \end{pmatrix}$$

$$= T(\vec{u}) + T(\vec{v})$$

A similar calculation shows that  $T(c\vec{u}) = cT(\vec{u})$ .

(b) Given the basis  $\alpha = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$  of  $\mathbb{R}^{2 \times 2}$ , give the matrix  $[T]_{\alpha}$  of T with respect to the basis  $\alpha$ .

$$T\left(\begin{array}{cc} 1 & 0 \\ 0 & 0 \end{array}\right) = \left(\begin{array}{cc} 1 & 0 \\ 0 & 4 \end{array}\right) = 1\left(\begin{array}{cc} 1 & 0 \\ 0 & 0 \end{array}\right) + 0\left(\begin{array}{cc} 0 & 1 \\ 0 & 0 \end{array}\right) + 0\left(\begin{array}{cc} 0 & 0 \\ 1 & 0 \end{array}\right) + 4\left(\begin{array}{cc} 0 & 0 \\ 0 & 1 \end{array}\right)$$

Thus the first column of  $[T]_{\alpha}$  is

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 4 \end{bmatrix}.$$

Proceeding similarly with the other columns, we get

$$[T]_{\alpha} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 1 & -3 & 2 \\ 4 & 0 & 0 & 1 \end{bmatrix}$$

(c) Show that T is an isomorphism, and use the determinant in your solution.

To show T is an isomorphism, one method is to show directly that T is invertible. We can accomplish this by showing that  $[T]_{\alpha}$  from part (b) is an invertible matrix. This, in turn, we can do by finding the determinant of  $[T]_{\alpha}$ . Expand along the first column to get

$$\det[T]_{\alpha} = \det\begin{bmatrix} -1 & 1 & 0 \\ 1 & -3 & 2 \\ 0 & 0 & 1 \end{bmatrix} - 4 \det\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -3 & 2 \end{bmatrix}$$
$$= \det\begin{bmatrix} -1 & 1 \\ 1 & -3 \end{bmatrix} - 4(1 \cdot 1 \cdot 2)$$
$$= (3 - 1) - 8 = -6$$

Since this determinant is non-zero, the matrix is invertible, and thus T is an isomorphism.

6. The mapping  $T: \mathbb{R}^2 \to P_2$  given by  $T\left(\left[\begin{array}{c} a_1 \\ a_2 \end{array}\right]\right) = (a_1 + a_2)x^2 + a_2x + a_1$  is a linear transformation.

(a) Prove that  $\alpha = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \end{bmatrix} \right\}$  is a basis for  $\mathbb{R}^2$  and  $\beta = \{x^2 + 2, x^2 + x, 1\}$  is a basis for  $P_2$ .

First note that  $\alpha$  is a basis for  $\mathbb{R}^2$  since  $\alpha$  is linearly independent (it is a set of two vectors and neither is a multiple of the other) and the dimension of  $\mathbb{R}^2$  is two. Similarly, one can check that  $\beta$  is linearly independent by assuming that  $c_1(x^2+2)+c_2(x^2+x)+c_3(1)=\vec{0}$ , setting up a system of equations involving  $c_1, c_2$ , and  $c_3$ , and showing that  $c_1 = c_2 = c_3 = 0$ . Since  $P_2(\mathbb{R})$  has dimension 3 this shows that  $\beta$  is a basis, by Theorem 3.3.4(c).

## (b) Find the matrix $[T]^{\beta}_{\alpha}$

To compute the first column of  $[T]^{\beta}_{\alpha}$ , we find T((1,2)) and write it in  $\beta$ -coordinates. We have

$$T((1,2)) = 3x^2 + 2x + 1 = 1(x^2 + 2) + 2(x^2 + x) - 1(1)$$

and thus the first column of  $[T]^{\beta}_{\alpha}$  is

$$\left[\begin{array}{c}1\\2\\-1\end{array}\right].$$

Note that to find the  $\beta$ -coordinates of  $3x^2 + 2x + 1$ , you can either eyeball a solution as follows: only  $x^2 + x$  involves x, and so we must have  $2(x^2 + x)$ , and then the only other term with  $x^2$  is  $x^2 + 2$ , so we must add on  $1(x^2 + 2)$  to get  $3x^2$ , then we have a constant term of 2, so we must subtract 1(1). Or you can take the more systematic approach of writing

$$3x^2 + 2x + 1 = a_1(x^2 + 2) + a_2(x^2 + x) + a_3(1),$$

which leads to the system of equations

$$\begin{array}{cccc} a_2 & +a_1 & = 3 \\ a_2 & & = 2 \\ a_3 & +2a_1 & = 1 \end{array}$$

which you can solve.

In the same way we can find the second column of  $[T]^{\beta}_{\alpha}$ , which gives

$$[T]_{\alpha}^{\beta} = \begin{bmatrix} 1 & -1 \\ 2 & 0 \\ -1 & 1 \end{bmatrix}$$

(c) What is the dimension of Ker(T)? Find a basis for Ker(T).

We put the augmented matrix

$$\left[ \begin{array}{cc|c}
1 & -1 & 0 \\
2 & 0 & 0 \\
-1 & 1 & 0
\end{array} \right]$$

In reduced row-echelon form, which gives

$$\left[ \begin{array}{cc|c}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 0
\end{array} \right]$$

There are no free variables, and hence  $\ker T = \{\vec{0}\}$ . So  $\ker T$  is zero-dimensional, and has basis  $\{\vec{0}\}$ .

(d) Since the dimension of ker T is zero, by the rank-nullity theorem we know that the dimension of the image of T must equal the dimension of  $\mathbb{R}^2$ , which is two. A basis of the image of the matrix  $[T]^{\beta}_{\alpha}$  is

$$\left\{ \begin{bmatrix} 1\\2\\-1 \end{bmatrix}, \begin{bmatrix} -1\\0\\1 \end{bmatrix} \right\}.$$

To turn this into a basis for the image of T, we need to re-convert these vectors (which are in  $\beta$ -coordinates) into elements of  $P_2$ . Doing so gives the two elements

$$1 \cdot (x^{2} + 2) + 2 \cdot (x^{2} + x) + (-1) \cdot 1 = 3x^{2} + 2x + 1$$
$$-1 \cdot (x^{2} + 2) + 0 \cdot (x^{2} + x) + (1) \cdot 1 = -x^{2} - 1$$

So  $\{3x^2 + 2x + 1, -x^2 - 1\}$  is a basis for the image of T.